1. Dijkstra fail. Construct a graph with integral lengths (without a negative cycle) where Dijkstra's algorithm would run exponentially long. (This is a variant of the algorithm which, if it relaxes a vertex $v$ and changes the estimate for its neighbor $u$, it opens the neighbor, that is, puts it in the priority queue even if it extracted it previously.)
2. Negative edges $+k$ ? Can we get rid of negative edges by adding some number $k \in \mathbb{N}$ to all edge lengths, so that we can use Dijkstra's algorithm to find the shortest path even in a graph with negative edges?
3. Generalized Shortest Paths. You are given a directed graph $G=(V, E)$ with edge lengths $\ell: E \rightarrow \mathbb{R}$ and vertex costs $c: V \rightarrow R$. For instance, imagine that this is a computer network and there is not only a delay for passing through a network cable, but also a delay incurred by passing through a router. The length of a path $v_{0}, e_{0}, v_{1}, e_{1}, \ldots, e_{k}, v_{k+1}$ is $\left(\sum_{i=0}^{k} c\left(v_{i}\right)\right)+\left(\sum_{i=0}^{k+1} \ell\left(e_{i}\right)\right)$. How to find the shortest paths from $s \in V$ to all other nodes in $G$ ?
4. Bellman-Ford. Suppose Bellman-Ford's algorithm is run on the following graph from node $A$ :


Draw a table displaying the intermediate values $h$ (the distance estimates for the nodes), and draw the final shortest-path tree.
5. Paths with at most $k$ edges. A graph $G$ with possibly negative edge lengths is given, and you are told that all shortest paths in $G$ contain at most $k$ edges. Construct an algorithm which, in time $\mathcal{O}(k|E|)$, solves the single-source shortest paths problem (for a given $s$, finds the shortest paths to all other vertices of $G$ ).
6. Shortest-paths Tree? You are given a directed graph $G=(V, E)$ with (possibly negative) weighted edges, along with a specific node $s \in V$ and a tree $T=\left(V, E_{0}\right), E_{0} \subseteq E$. Give an algorithm that checks whether $T$ is a shortest-path tree for $G$ with starting point $s$. Your algorithm should run in linear time.
7. All-pairs, through $v_{0}$. You are given a strongly connected directed graph $G=(V, E)$ with positive edge weights along with a particular node $v_{0} \in V$. Give an efficient algorithm for finding shortest paths between all pairs of nodes, with the one restriction that these paths must all pass through $v_{0}$.
8. Currency Exchange. A currency exchange trades $n$ currencies (say that currency number one is CZK) and it announces a matrix of exchange rates $K$. The exchange rate $K_{i j}$ says how many units of currency $j$ we get for one unit of currency $i$. Design an algorithm which decides whether there exists a sequence of currency exchanges which begins with 1 CZK and ends with $>1$ CZK.
9. Dijkstra with Small Lengths. Suppose we want to run Dijkstra's algorithm on a graph whose edge weights are integers in the range $0,1, \ldots, W$, where $W$ is a relatively small number.
(1) Show how Dijkstra's algorithm can be made to run in time $\mathcal{O}(W|V|+|E|)$.
(2) Show an alternative implementation that takes time just $\mathcal{O}((|V|+|E|) \log W)$.
10. Floyd-Warshall and Shortest Cycle. Modify Floyd-Warshall's algorithm to detect, for each vertex $v$, the shortest cycle in $G$ containing $v$. (Assume $G$ has no negative cycles.)
11. Edges on Shortest Paths. Construct an algorithm which detects all edges lying on at least one shortest path from $s$ to any vertex, or from $s$ to a particular vertex $t$
12. Critical Edges. Say that an edge $e$ is critical for $s$ if removing it from $G$ changes the distances from $s \in V$, that is, there exists a $v$ such that $d_{G}(s, v)<d_{G-e}(s, v)$. Design an algorithm which detects all edges critical for $s$.

